

## Method for the fault tolerant position detection of an object

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**Inventor:** REHKOPF ANDREAS DR-ING (DE)

**Applicant:** SIEMENS AG (DE)

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**Cited documents:**

US5311195  
US5525998  
US5129605  
US5311173

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### Abstract of EP0825418

The method involves acquiring individual position statements (P1..Pn) with individual quality from several sensors (S1..Sn) e.g. odometer, axle counter, beacon, inertial sensor or radar, during evaluation time periods (It). The individual position statements are used after equalization with sensor-specific weighing factors for determining respectively an actual object position (OP) at the evaluation time. Object position estimates for the next evaluation time period are undertaken under consideration of object dynamics, based on the sensor-individual position statements. The weighing factors are continuously increased or decreased, based on evaluation of the quality of the object position estimates and the actual position values.

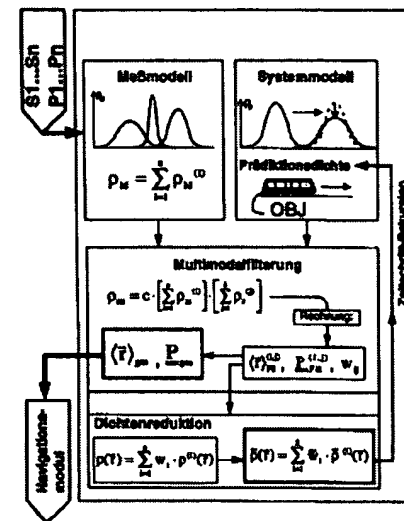


FIG 6

Data supplied from the esp@cenet database - Worldwide

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